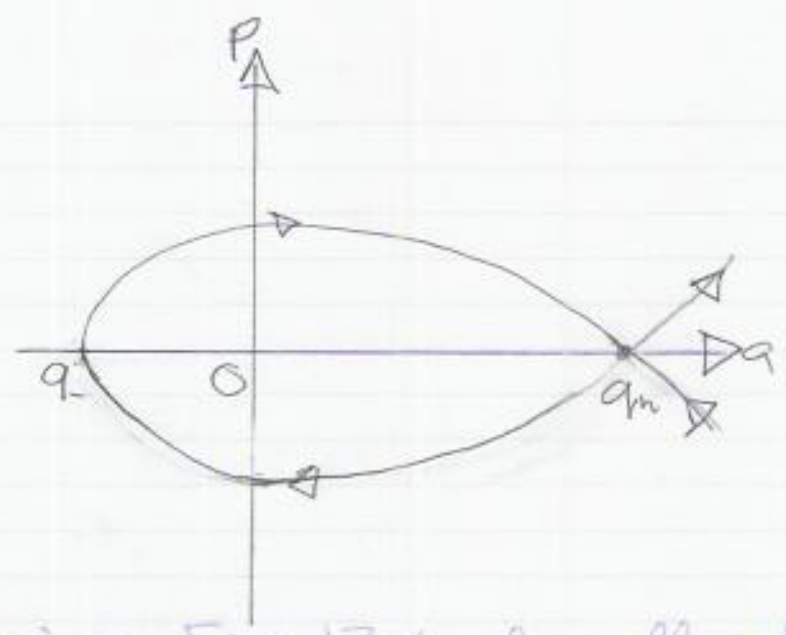


3)



Explain notation

Using Fig 13.4 for illustrative purposes, choose  $q(0) = q_1$  where  $q_1$  is as shown on the diagram ( $q_n = q(0)$ ) will also give  $p(t) = -p(-t)$  but we would not have  $\lim_{t \rightarrow \pm \infty} q_s(t) = q_n$

Since  $q_n$  is a (saddle) hyperbolic fixed point

From the symmetry of the separatrix  $q_s(p) = q_s(-p)$ . From the uniqueness of solutions of differential eqns.

If we solve for  $q$  in terms of  $t$  the eqn  $t = \int_{q_n}^q \frac{dq}{\sqrt{2(E - V(q))}}$

and then, since  $p = \dot{q}$ , for  $p$  in terms of  $t$ , we can put  $q_s(p(t)) = q_s(-p(t))$  but since with the initial conditions given, the solutions for  $q$  and  $p$  are unique we must have that  $p(t) = -p(-t)$  so that  $q_s(p(t)) = q_s(-p(-t))$  becomes

$$q_s(p(t)) = q_s(-p(-t))$$

$$q_s(p(t)) = q_s(-(-p(t))) = q_s(p(t))$$

to conform to this uniqueness condition.

Thus  $q_s(t)$  is even and  $p_s(t)$  is odd  
 i.e.  $q_s(t) = q_s(-t)$   
 $p_s(t) = -p_s(-t)$

Meaning of ~~Form of Hamilton's equations~~ ~~phase portrait~~ ~~Form of Hamilton's~~ for  $-t$   
 $p(-t)$   $q(-t)$  etc.

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