

$$\begin{aligned}
&= (Vf) \langle X, \omega_1 \rangle + f V \langle X, \omega_1 \rangle - f \langle L_V X, \omega_1 \rangle \\
&= Vf \langle X, \omega_1 \rangle + f \langle L_V X, \omega_1 \rangle + f \langle X, L_V \omega_1 \rangle - f \langle L_V X, \omega_1 \rangle \\
&= Vf \langle X, \omega_1 \rangle + f \langle X, L_V \omega_1 \rangle \\
&= Vf \omega_1(X) + f(L_V \omega_1)(X) \\
&= Vf \omega_1 + f L_V \omega_1
\end{aligned}$$

Since  $X$  is arbitrary, ✓

iv) Evaluate on RHS and LHS separately.

$$\begin{aligned}
\text{RHS: } \langle X, L_V \omega \rangle &= \langle C_1 \partial_1 + C_2 \partial_2, L_{a, \partial_1}(b, \omega_1) \rangle \\
&= \langle C_1 \partial_1 + C_2 \partial_2, a_1 \partial_1(b) \omega_1 + b_1 L_{a, \partial_1}(\omega_1) \rangle
\end{aligned}$$

We need to find  $L_{a, \partial_1}(\omega_1)$ .  
Curve through  $(x^1, x^2)$  with tangent vector  $a, \partial_1$  is given by  $(a, t + x^1, x^2) = d$ .

$$\begin{aligned}
d^*(\omega_1) &= dd^1 = d(a, t + x^1) \\
&= (\partial_1 a_1) t \omega_1 + (\partial_2 a_1) t \omega_2 \\
&\Rightarrow L_V \omega_1 = (\partial_1 a_1) \omega_1 + (\partial_2 a_1) \omega_2
\end{aligned}$$

$$\begin{aligned}
&\Rightarrow \langle C_1 \partial_1 + C_2 \partial_2, a_1 \partial_1(b) \omega_1 + b_1 L_{a, \partial_1}(\omega_1) \rangle \\
&= \langle C_1 \partial_1 + C_2 \partial_2, (a_1 \partial_1(b) + b_1 (\partial_2 a_1)) \omega_1 + b_1 (\partial_2 a_1) \omega_2 \rangle \\
&= C_1 a_1 (\partial_1 b) + C_2 b_1 (\partial_2 a_1) + C_2 b_1 (\partial_2 a_1) = (L_V \omega)(X)
\end{aligned}$$

$$\begin{aligned}
\text{RHS } d(V \lrcorner \omega)(X) &= \langle X, d(V \lrcorner \omega) \rangle \\
&= \langle C_1 \partial_1 + C_2 \partial_2, d(a_1 \partial_1(b, \omega_1)) \rangle \\
&= \langle C_1 \partial_1 + C_2 \partial_2, d(a_1, b) \rangle \\
&= \langle C_1 \partial_1 + C_2 \partial_2, (a_1 \partial_1(b) + (\partial_1 a_1) b) \omega_1 + (a_1 \partial_2(b) + (\partial_2 a_1) b) \omega_2 \rangle \\
&= C_1 a_1 (\partial_1 b) + C_1 (\partial_1 a_1) b_1 + C_2 a_1 \partial_2 b_1 + C_2 (\partial_2 a_1) b_1
\end{aligned}$$

and

$$\begin{aligned}
(V \lrcorner d\omega)(X) &= \langle C_1 \partial_1 + C_2 \partial_2, a_1 \partial_1 \lrcorner d(b, \omega_1) \rangle \\
&= \langle C_1 \partial_1 + C_2 \partial_2, a_1 \partial_1 \lrcorner (\partial_1 b \omega_1 \wedge \omega_1 - \partial_2 b \omega_1 \wedge \omega_2) \rangle
\end{aligned}$$