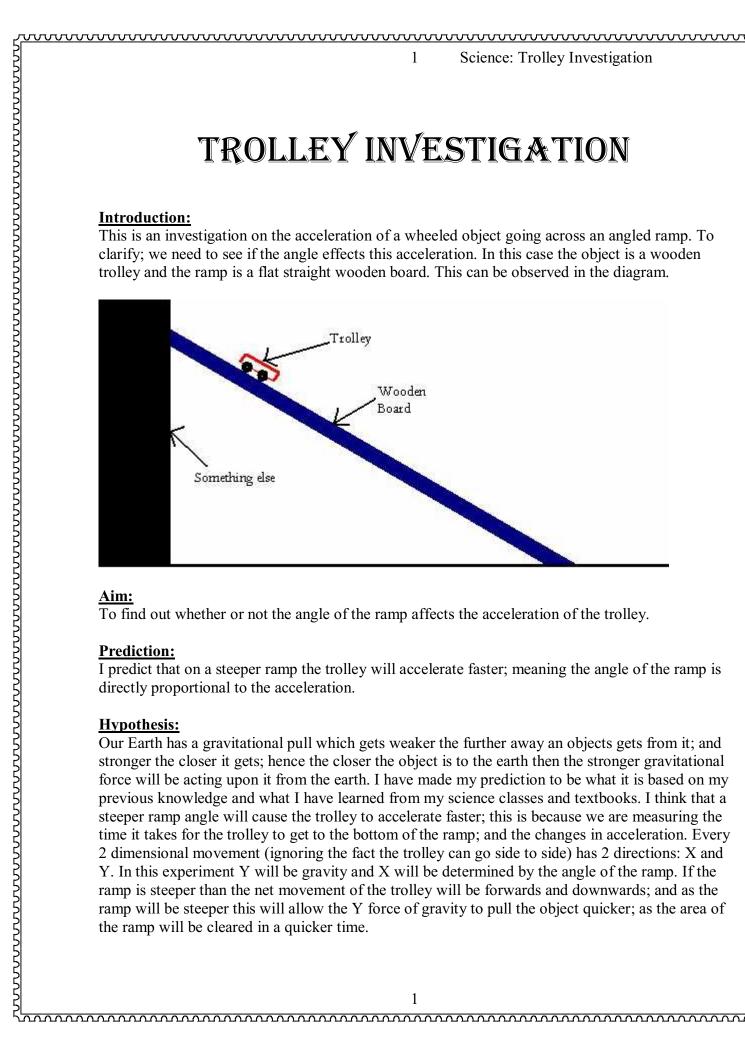
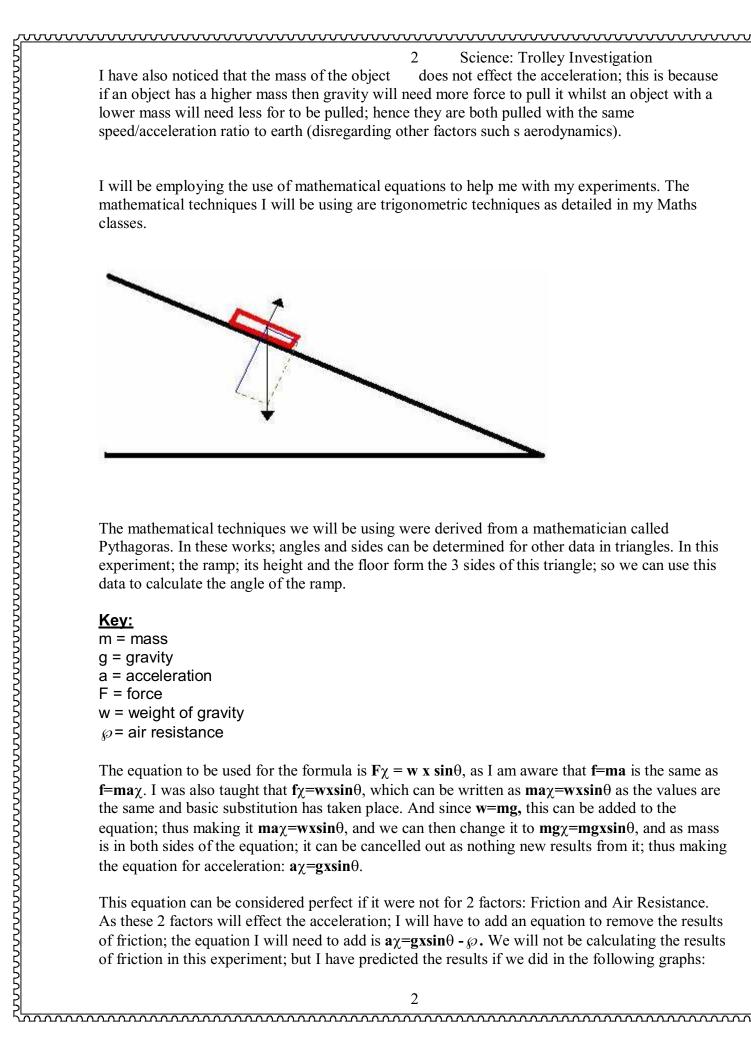
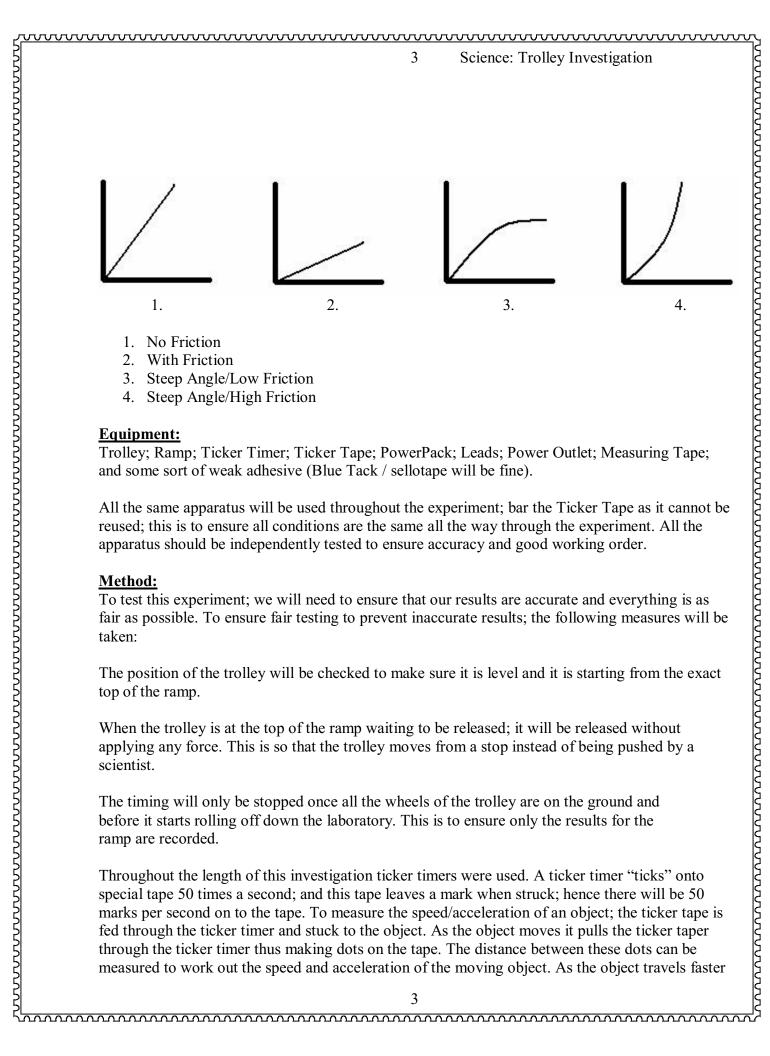
$\overline{v}$ 

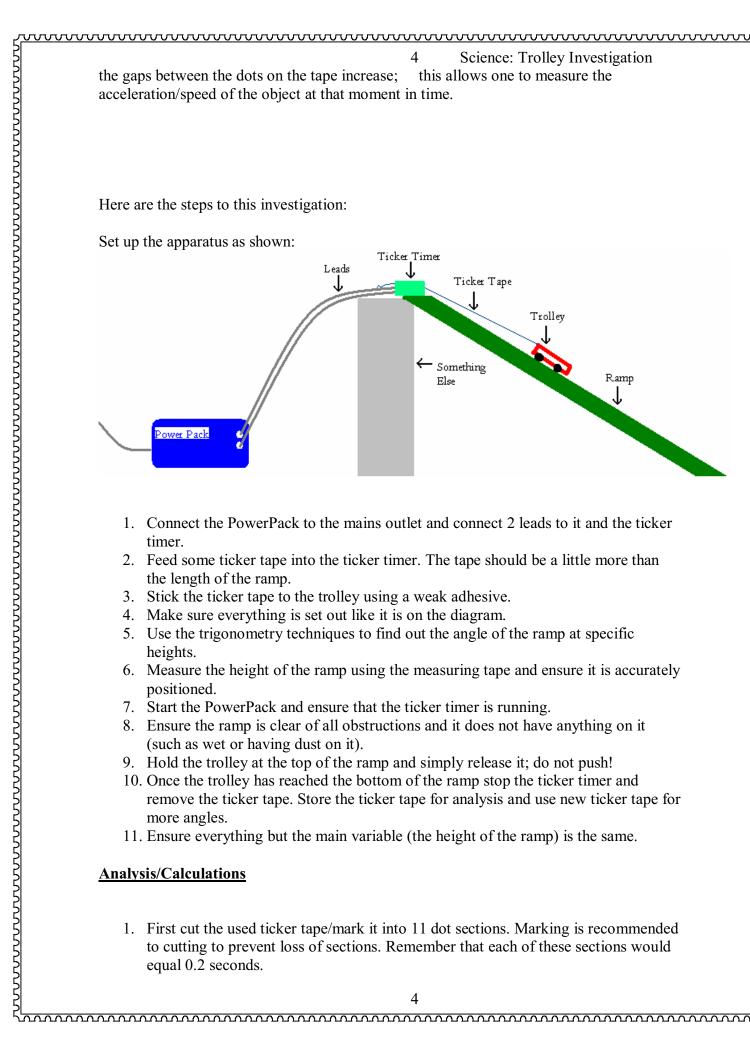




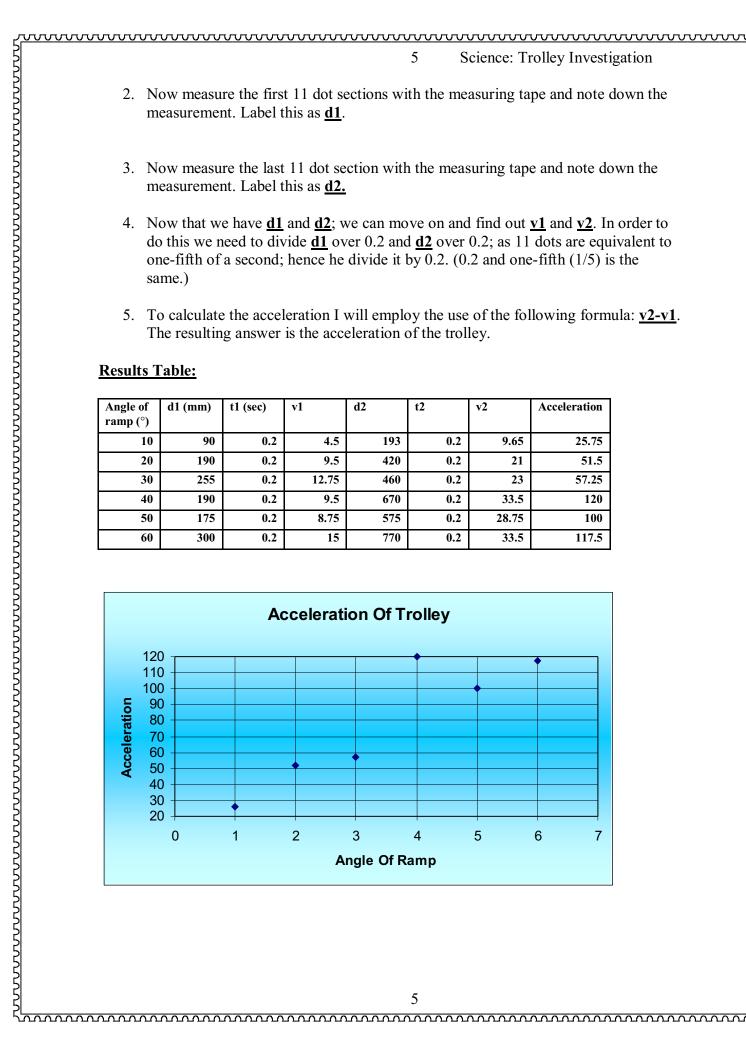
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 $\overline{v}$ 



Angle of ramp (°)	d1 (mm)	t1 (sec)	v1	d2	t2	v2	Acceleration
10	90	0.2	4.5	193	0.2	9.65	25.75
20	190	0.2	9.5	420	0.2	21	51.5
30	255	0.2	12.75	460	0.2	23	57.25
40	190	0.2	9.5	670	0.2	33.5	120
50	175	0.2	8.75	575	0.2	28.75	100
60	300	0.2	15	770	0.2	33.5	117.5



Conclusion:

The line of best lit shows that my prediction was correct; meaning that a steeper angled ramp results in a laster acceleration of the trolley. My prediction was correct; this is because once the angle of the ramp increases the trolley is being pulled faster down to the ground by gravity and the ramp's horizontal co-efficient decreases. Simply; if the ramp is steeper; then the trolley will alb be pulled down it; but as it cannot go through the ramp is steeper, then the trolley will get down faster as it will use most of its potential energy going downwards instead of going forwards down the ramp.

Evaluation:

I think this experiment went along really well and the results were reliable; but the anomaly. I think that my predictions were good from my previous knowledge and my hypothesis was improved upon after I did the experiment. I have learnt much more about this topic than I thought I would and it was academically rewarding.

There were 2 anomalies; one major anomaly and one minor anomaly. The major anomaly was recorded at 40°; whilst the minor one was recorded at 20°. The major anomaly at 40° was 40 units from the expected value. This could have possibly been because the calculations were misread by someone or perhaps the data was input incorrectly into the calculations. If we had a larger timescale we would have repeated these anomalous results in the same conditions to ensure a fair test. I think the major poblem here was the factor of human error. This problem can be prevented in the fluture by having someone to continuously supervise the experiment and its necessary steps to ensure that these problems do not happen. I think the results were reliable none-the-less if the anomalies were ignored and a line of best fit was drawn on the graph. If I look back on my predictions and I have ideas on how they can be improved. A problem was that the ticker timer and the ticker tape were causing a frictional effect on the trolley. This problem can be solved with the aid of light gates as these are newer;

